SENATE No.

The Commonwealth of Massachusetts

PRESENTED BY:

William J. Driscoll

To the Honorable Senate and House of Representatives of the Commonwealth of Massachusetts in General Court assembled:

The undersigned legislators and/or citizens respectfully petition for the adoption of the accompanying bill:

An Act relative to providing multimodal transportation technologies.

PETITION OF:

NAME:DISTRICT/ADDRESS:William J. DriscollNorfolk, Plymouth and Bristol

SENATE No.

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The Commonwealth of Massachusetts

In the One Hundred and Ninety-Fourth General Court (2025-2026)

An Act relative to providing multimodal transportation technologies.

Be it enacted by the Senate and House of Representatives in General Court assembled, and by the authority of the same, as follows:

- SECTION 1. Chapter 90 of the General Laws is hereby amended by adding the following new section: -
- 19L. As used in the chapter, the following words shall have the following meanings
 unless the context clearly requires otherwise:
- "Automated driving system" means hardware and software that are collectively capable
 of performing the entire dynamic driving task on a sustained basis, regardless of whether it is
 limited to a specific operational design domain.
- 8 "Department" The Massachusetts Department of Transportation established under the 9 provisions of Chapter 6C of the General laws.
 - "Dynamic driving task" or "DDT" means all of the real-time operational and tactical functions required to operate a vehicle in on-road traffic, including i. Lateral vehicle motion control via steering; ii. Longitudinal motion control via acceleration and deceleration; iii.

Monitoring the driving environment via object and event detection, recognition, classification, and response preparation; iv. Object and event response execution; v. Maneuver planning; and vi. Enhancing conspicuity via lighting, signaling, and gesturing. This definition shall not include the strategic functions of trip scheduling and, or the selection of destinations and waypoints.

"DDT fallback" means the response by the person or human driver to either perform the DDT or achieve a minimal risk condition after occurrence of a DDT performance relevant system failure, or upon operational design domain exit; or the response by an automated driving system to achieve minimal risk condition, given the same circumstances

"Fully autonomous vehicle" means a motor vehicle equipped with an automated driving system designed to function without a human driver as a level 4 or 5 system under SAE J3016B standards;

"Human driver" means a natural person in the vehicle with a valid driver's license who controls all or part of the dynamic driving task.

"Minimal risk condition" means a condition to which a person, a human driver, or an automated driving system may bring a vehicle after performing the DDT fallback in order to reduce the risk of a crash when a given trip cannot or should not be completed.

"On-Demand Autonomous Vehicle Network" means a transportation service network that uses a software application or other digital means to dispatch or otherwise enable the prearrangement of transportation with fully autonomous vehicles for purposes of transporting passenger goods, including for-hire transportation of passengers or goods for compensation. "Operational Design Domain" means the operating conditions under which a given automated driving system is specifically designed to function, including but not limited to (i) environmental, geographical, and time-of-day restrictions and (ii) the requisite presence or absence of certain traffic and roadway characteristics.

"Person" means a natural person, corporation, business trust, estate, trust, partnership, limited liability company, association, joint venture, governmental agency, public corporation or any other legal or commercial entity.

"Request to intervene" means a notification by an automated driving system to a human driver that the human driver should promptly begin or resume performance of part of or all of the dynamic driving task.

"SAE J3016" means the "Taxonomy and Definitions for Terms Related to Driving

Automation Systems for On-Road Motor Vehicles" published by SAE International on June 15,

2018, as revised.

SECTION 2. A person may operate on the highways in the commonwealth a fully autonomous vehicle or a motor vehicle equipped with an automated driving system capable of performing the entire dynamic driving task with the automated driving system engaged without a human driver if the vehicle meets the following conditions: i.the vehicle meets the requirements of this chapter and has been issued an autonomous operation license by the Department; ii. if a failure of the automated driving system occurs that renders that system unable to perform the entire dynamic driving task relevant to its intended operational design domain, the vehicle will achieve a minimal risk condition and, if there is a human driver physically present in the vehicle, issue a request to intervene with the expectation that the human driver will respond appropriately

to such request; iii. the vehicle is capable of operating in compliance with the applicable traffic and motor vehicle safety laws and regulations of the Commonwealth when it is reasonable to do so unless an exemption has been granted by the Department; iv. when required by federal law, the vehicle bears the required manufacturer's certification label indicating that at the time of its manufacture it has been certified to be in compliance with all applicable federal motor vehicle safety standards, including any exemptions granted by the National Highway Traffic Safety Administration.

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A fully autonomous vehicle for which the declared gross weight of the vehicle and any towed unit is 10,000 pounds or heavier shall have a human driver, with the appropriate credentials to operate the vehicle, physically present in the vehicle to monitor the performance of the vehicle and intervene if necessary. Prior to operating a fully autonomous vehicle in the Commonwealth without a human driver, a person shall submit a law-enforcement interaction plan to the Department of Transportation, Department of Public Safety and the police department of the city, town or jurisdiction where a vehicle will be operating that describes (i) how to communicate with a fleet support specialist who is available during the times the vehicle is in operation, (ii) how to safely remove the fully autonomous vehicle from the highway and steps to safely tow the vehicle, (iii) how to recognize whether the automated driving system is engaged on the fully autonomous vehicle, and (iv) any additional information the manufacturer or owner deems necessary regarding hazardous conditions or public safety risks associated with the operation of the fully autonomous vehicle. In the event of a crash the fully autonomous vehicle shall remain on the scene in accordance with state law. The owner of the fully autonomous vehicle, or a person on behalf of the vehicle owner, shall report any crashes or collisions in accordance with state law.

SECTION 3. The Department shall develop and issue autonomous operation licenses for fully autonomous vehicles and automated driving systems operated in the Commonwealth. The Department shall only issue such autonomous operation licenses to fully autonomous vehicles and automated driving systems that meet the requirements of this chapter. A fully autonomous vehicle shall be properly titled and registered in accordance with the requirements of this chapter. If a fully autonomous vehicle is registered in the Commonwealth, the vehicle shall be identified on the registration as a fully autonomous vehicle. The requirements under this act relating to exhibiting a driver's license and registration card are satisfied if the autonomous operation license and vehicle registration card are in the fully autonomous vehicle and available for inspection by a law-enforcement officer. When an automated driving system installed on a motor vehicle is engaged, the automated driving system is considered the driver or operator for the purpose of assessing compliance with applicable traffic or motor vehicle laws and shall be required to satisfy all physical acts required by a driver or operator of the vehicle.

SECTION 4. Before operating a fully autonomous vehicle on public roads in the commonwealth without a human driver, a person shall submit proof of financial responsibility to the Department that the fully autonomous vehicle is covered by insurance or proof of self-insurance in accordance with the provisions of Chapter 175 of the Massachusetts General Laws. Such coverage shall be primary, however, and the minimum amount of liability coverage for death, bodily injury, and property damage shall be \$1 million.

SECTION 5. Nothing in this chapter shall be construed to (i) prohibit a human driver from operating a fully autonomous vehicle to control all or part of the DDT, (ii) prohibit a fully autonomous vehicle from operating without a human driver except as provided in this Act, (iii)

prohibit a human driver from operating a vehicle with an automated driving system that is not a fully autonomous vehicle with such system engaged or disengaged, or (iv) apply to toy vehicles.

SECTION 6. An on-demand autonomous vehicle network shall be permitted to operate in the Commonwealth in accordance with the provisions of this Act under the jurisdiction of the Department.

SECTION 7. A fully autonomous vehicle shall be properly registered in accordance with the provisions of this Chapter. If a fully autonomous vehicle is registered in the Commonwealth, the vehicle shall be identified on the title as a fully autonomous vehicle. A fully autonomous vehicle shall be properly titled in accordance with the provisions of this Chapter. If a fully autonomous vehicle is registered in the Commonwealth, the vehicle shall be identified on the title as a fully autonomous vehicle.

SECTION 8. A person may operate a motor vehicle equipped with an automated driving system capable of performing the entire dynamic driving task if (i) such automated driving system will issue a request to intervene whenever the automated driving system is not capable of performing the entire dynamic driving task with the expectation that the person will respond appropriately to such a request; and (ii) the automated driving system is capable of being operated in compliance with the provisions of this chapter.

Nothing in this Act shall prohibit or restrict a human driver from operating a fully autonomous vehicle equipped with controls that allow the human driver to control all or part of the dynamic driving task.

SECTION 9. A fully autonomous vehicle that is also a commercial motor vehicle pursuant to the provisions of this chapter governing the operation of commercial motor vehicles,

except that any provision that by its nature reasonably applies only to a human driver does not apply to such a vehicle operating with the automated driving system engaged.

SECTION 10. A fully autonomous vehicle that is designed to be operated exclusively by the automated driving system for all trips is not subject to motor vehicle equipment laws or regulations of this state that: (1) relate to or support motor vehicle operation by a human driver seated in the vehicle; and (2) are not relevant for an automated driving system.

SECTION 11. Unless otherwise provided in this chapter and notwithstanding any other provision of law, fully autonomous vehicles and automated driving systems are governed exclusively by the provisions of this Act. No state agency, political subdivision, municipality, or local entity may prohibit the operation of fully autonomous vehicles, automated driving systems, or on-demand autonomous vehicle networks, or otherwise enact or keep in force rules or ordinances that would impose taxes, fees, or other requirements (including performance standards), specific to the operation of fully autonomous vehicles, automated driving systems, or on-demand autonomous vehicle networks in addition to the requirements of this Act.